Model MA36S MultiTurn Absolute





Features

- Standard Size 36 mm Package
- Durable Magnetic Technology
- Multiturn Absolute Encoder (12 Bit/40 Bit)
- · SSI and CANopen Communications
- · Proven New Turns Counting Technology No Gears or Batteries

The Model MA36S Multiturn Absolute is ideal for a wide variety of industrial applications that require an encoder with the capability of absolute positioning output. Its fully digital output and innovative use of battery-free multiturn technology make the Model MA36S an excellent choice for all applications, especially ones with a high presence of noise. Its durable magnetic technology and high sealing make it a perfect choise for dirty industrial environments. Available with a 6 mm or 1/4" shaft and a servo mount, the Model MA36S is easily designed into a variety of applications.

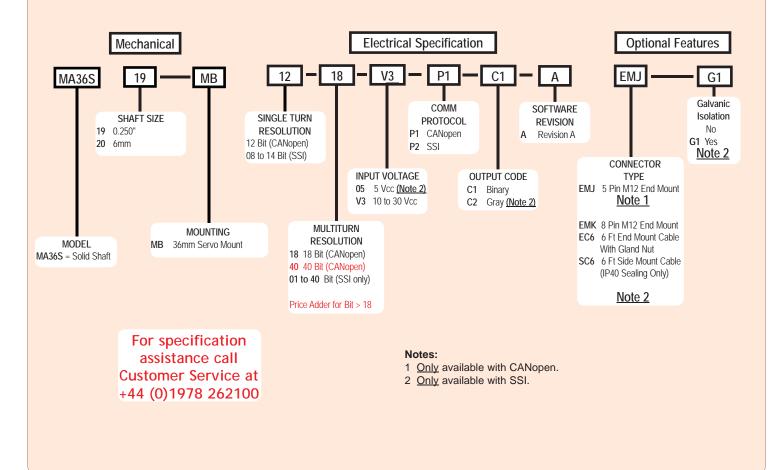
Common Applications

Robotics, Telescopes, Antennas, Medical Scanners, Windmills, Elevators, Lifts, Motors, Automatic Guided Vehicles, Rotary and X/Y Positioning Tables

Model MA36S Ordering Guide

For Single turn applications see Model SA36S

Red type indicates price adder options. Not all configuration combinations may be available. Contact Customer Service for details.



BRITISH ENCODER PRODUCTS Co, UNIT 33 WHITEGATE INDUSTRIAL ESTATE, WREXHAM, LL13 8UG, UNITED KINGDOM TEL: +44 (0)1978 262100 - FAX: +44 (0)1978 262101 - WEB: WWW.ENCODER.CO.UK - EMAIL: SALES@ENCODER.CO.UK

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Model MA36S Specifications

Electrical

Electrical			
Input Voltage	. 10 to 30 Vcc max SSI or CAN		
	5 Vcc SSI Only		
Input Current	50 mA max with no external load		
Power Consumption	1.0.5 W max		
Resolution	12 bit (CAN)		
	8 to 14 bit (SSI)		
Accuracy	Less than .15° (CANopen)		
	Less than .35° (SSI)		
CANopen Interface)		
Protocol	. CANopen:		
	- Communication profile CiA 301		
	- Device profile for encoder CiA 406		
	V3.2 class C2		
Node Number	.0 to 127 (default 127)		
	.10 Kbaud to 1 Mbaud with automatic bit		
	rate detection		
The standard setti	ngs as well as any customization in the		
	nanged via LSS (CiA 305) and the SDO		
protocol, e.g. PDOs, scaling, heartbeat, node-ID, baud rate,			
etc			
Programmable CAN Transmission Modes			
Synchronous	. When a synchronisation telegram		
<u>,</u>	(SYNC) is received from another bus		
	node, PDOs are transmitted independ-		
	and the second		
	antly		

	anuy
Asynchronous	. A PDO message is triggered by an
	internal event (e.g. change of measured
	value, internal timer, etc.)

SSI Interface

Clock Inputvia opto coupler
Clock Frequency 100KHz to 500KHz
Data Output RS485 / RS422 compatable
Output Code Gray or binary
SSI Output Angular position value
Parity Bit Optional (even/odd)
Error Bit Optional
Turn On Time<1.5 sec
Pos. Counting Dir Connect DIR to GND for CW
Connect DIR to VDC for CCW
(when viewed from shaft end)
Set to Zero Apply Vcc for 2 sec

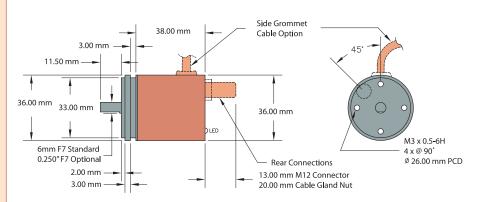
Mechanical

Max Shaft Speed	12,000 RPM
Shaft Size	6 mm, 0.250"
Radial Shaft Load	7 lb (32 N) = bearing life 1.10 ¹⁰ revs
	3.6 lb (16 N) = bearing life 1.10 ¹¹ revs
Axial Shaft Load	5 lb (20 N) = bearing life 1.10 ¹⁰ revs
	2.3 lb (10 N) = bearing life 1.10^{11} revs
Starting Torque	<0.45 oz-in typical
	Ferrous chrome-plated magnetic screening
	Flange or servo type
Weight	
5	5 51

Environmental

Operating Temp40° to +80° C
Storage Temp40° to +100° C
Humidity95% RH non-condensing
Vibration5 g @ 10 to 2000 Hz
Shock100 g @ 6 ms duration
SealingIP64, shaft sealed to IP65

Model MA36S Solid Shaft



Wiring Table

CANopen Encoders

Function	Pin	
υ _B	2	
Ground (GND)	3	
CAN _{High}	4	
CANLOW	5	3
CAN _{GND} / shield	1	

SSI Encoders

	8-pin M12	Cable
Function		
Ground (GND)	1	White
+Vcc	2	Brown
SSI CLK+	3	Green
SSI CLK-	4	Yellow
SSI DATA+	5	Gray
SSI DATA-	6	Pink
PRESET	7	Blue
DIR	8	Red
Shield	housing	Side Exit - Housing End Exit - N/C

Rev A