Technology that inspires



PRODUCT RANGE

Mechanics | Software | Electronics





Four steps to perfect automation





The high dynamic linear motor axis HL

The linear motor axis HL provides, without any doubt, the most modern drive technology which is highly integrated and ready to mount. Tight and precise recirculating ball bearings and an absolute measurement system as well as the automatic lubrication are all included in this product.

The result: Rapid and harmonic movements, horizontal or vertical mounting and loading on the rigth or left side is possible.





Options available:

- Tool-Connector; electical and pneumatic supply is accessible.
- Automatic grease pump for application without maintenance.



Fast, easy and secure setting through its unique user software.



Safer vertical mounting through high power clamping module

The key advantages at a glance:

- User programmable
- Extreme dynamics
- Monitored movements
- Long lifetime
- No maintenance cost
- Compact architecture
- Stiff mechanical assembling
- No oil / No gear
- Various sizes and shapes available
- Absolute encoder (up to 500 mm)
- Light weight
- High power density
- No wearing parts

HL 50

Technical data

Cont. force (N):	65	Cont. current (Arms):	2.4
Peak force (N):	180	Peak current (Arms):	6.0
Max. speed(m/s):	4	Max. load capacity (kg):	6
Max. acceleration (m/s²):	40	Max. DC-Voltage (VDC):	800

System-accuracy (μm/m):	10	incremental (Sin/Cos 1 Vpp)
System-accuracy (µm/m):	5	absolute (BISS/C, SSI) optional
Repeatability (µm):	5	incremental (Sin/Cos 1 Vpp)
Repeatability (µm):	2	absolute (BISS/C, SSI) optional
Brake force per unit (N):	200	
Available stroke(mm):	150, 300	
Thermal sensor:	PTC	
Weight: St	eel base	Alu base
Weight of rail, 0 stroke (kg):	0.7	0.7
Weight of rail/100mm (kg):	0.3	0.3
Weight of narrow motor (kg):	2.5	2.1
Weight of wide motor (kg):	2.9	2.2
Weight of brake (kg/piece):	0.4	0.4

Static load



Dynamic load

			↓	↓ ====
20Nm	30Nm	10Nm	60N	90N

Timing diagram



Dimensions HL 50



	Number of brakes			
	0	1	2	
150	310	359	408	L+110
300	460	509	558	L+110

HL100

Technical data

Cont. force (N):	150	Cont. current (Arms):	3.6
Peak force (N):	380	Peak current (Arms):	9.5
Max. speed(m/s):	4	Max. load capacity (kg):	10
Max. acceleration (m/s²):	40	Max. DC-Voltage (VDC):	800

System-accuracy (µm/m):	10	incremental (Sin/Cos 1 Vpp)
System-accuracy (µm/m):	5	absolute (BISS/C, SSI) optional
Repeatability (µm):	5	incremental (Sin/Cos 1 Vpp)
Repeatability (μm):	2	absolute (BISS/C, SSI) optional
Brake force per unit (N):	200	
Available stroke(mm):	150, 300, 450	
Thermal sensor:	PTC	
Weight:	Steel base	Alu base
Weight of rail, 0 stroke (kg):	1.8	1.8
Weight of rail/100mm (kg):	0.6	0.6
Weight of narrow motor (kg):	4.4	3.6
Weight of wide motor (kg):	5.1	4
Weight of brake (kg/piece):	0.5	0.5

Static load

~		C		
350Nm	500Nm	100Nm	400N	800N

Dynamic load

c			↓	
35Nm	40Nm	15Nm	100N	150N

Timing diagram



Dimensions HL 100



WAS – WEISS Application Software

In addition to the basic functions of the start up, WAS – WEISS Application Software also gives you easy access to the teaching of positions an programming of motion-sequences. Your Windows-PC will be connected through RS232 or Ethernet with our drive.

Co	ommunication
•	Profibus-DP
•	Digital I/O
•	Free ASCII protocol
•	Ethernet
•	DeviceNet-CAN
•	EtherNet/IP
•	Modbus TCP
•	CAN
So	oftware
•	All positions and speeds are user programmable
•	Up to 128 teaching positions
•	Up to 32 prgrams can be stored
•	Ability to force inputs an outouts (e.g. for initial start-up)
•	Software cam-functions can be defined







Machine Layout linear axis HL

□ Enquiry □ Enclosure with order

Dear customer,

Thank you for your interest in our handling units. To ensure optimum design of the system for your specific requirements, please answer the following questions:

Single axis

INUTTION AXES:	Number of HG axes:	Number of HL axes:
A CONTRACTOR OF THE OWNER OWNER OWNER OF THE OWNER OWNE		 Without brake (hor.) brake (vertical) 2 brakes (vertical)
Stroke: mm	Stroke: mm	Stroke: mm
Axis system		
No. of HP handling units:	No. of linear gantries:	No. of cross-tables:
C+		
Y stroke: mm	X stroke: mm	X stroke: mm
Z stroke: mm	Z stroke: mm	Y stroke: mm
No. of 3-axis handling units:	No. of gantry handling uni	ts: No. of 3-axis handling units:
	1 K	ALL STREET
X stroke: mm	X stroke: mm	X stroke: mm
Y stroke: mm	Y stroke: mm	Y stroke: mm
Z stroke: mm	Z stroke: mm	Z stroke: mm
Cycle calculation Axis	Stroke Time	Electrical components
Payload: kg	A	□ WEISS control package
1		Amplifier, WAS software
2 3		Cable lengths: □ 5m □ 10m □ 15m □ 20m □ 25m
2 3 4		Cable lengths: 5m 10m 15m 20m 25m 25m Interface to customer PLC
2 3 4 5 6		Cable lengths: Therefore to customer PLC Ethernet Ethernet
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2 3 4 5 6 7 8 9 10		Cable lengths: Therface to customer PLC Ethernet Profibus-DP* digital I/O CAN bus free ASCII protocol DeviceNet-CAN (Rockwell)
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2 3 4 5 6 7 8 9 10 10 Accessories Measuring system □ incremental Lubrigation	absolute (up to 1000mm s	Cable lengths:
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