Technology that inspires



PRODUCT RANGE

Mechanics | Software | Electronics



freely programmable

00.0



Four steps to perfect automation





The TW with Hybrid-Drive

A direct drive motor integrated with a high-precision gear, absolute encoder and built-in brake combined with a robust mechanical platform.

The TW sets new standards in the compact rotary indexing table-area in the following characteristics: dynamic, precision, user programmable and ease of use, power density. These products are designed to greatly outperform any pneumatic indexing solutions available.

Additional user benefits: Comparable in cost to pneumatic solutions, a clear cost advantage is developed through enhancement in productivity, lower operating cost and reduced maintenance cost.



Available in three sizes





Fast, easy and secure setting through ist unique user software.

The key advantages at a glance:

- User programmable
- Much faster than pneumatic solution
- Much more precise than pneumatic solution
- Higher power density than pneumatic solution
- Very little dwelltime
- Absolute encoder
- Precise zero-point through locating holes in the body
- No wear
- Precise teaching of each position
- Rigid stationary center section in various levels
- Electronic overload protection
- Any mounting position possible
- High energy efficiency
- Indexing in any angles possible

TW 150

Technical data

Cont. torque (Nm):	33	Cont. current (Arms):	2
Peak torque (Nm):	75	Peak current (Arms):	5
Max. speed (rpm):	80	Radial run out (mm):	0.02
Friction (Nm):	5	Axial run out at Ø 140 (mm):	0.02
Max. load (kgm²):	5	Thermal sensor:	PTC
Index precision (″):	±65	Internal inertia (kgm²):	0.0054
Max. DC-Voltage (VDC):	800	Weight (kg):	27
Mounting Position:	any*	Gear ratio:	1:9
		All values in relation to the table-top	

Encoder

Interface Sick-Stegmann Hiperface		Interface Heidenhain EnDat (on request)			
Accuracy:	SEL52	±65"	Accuracy:	EQI	±65"

Load data (for the stationary center section)

		1			
perm. tilting moment acting on the center section	200 Nm	perm. force acting vertically on the center section	3500 N	perm torque acting on the center section	150 Nm
perm. radial force acting on the center section	2500 N				
Load data (for the rotary in	doving dial plato)				

LOAD DATA (for the rotary indexing dial plate)

perm. tilting moment acting on the locked dial plate	500 Nm	perm. operating force (acting verti- cally on the locked dial plate with the nominal Ø) 5500 N	perm. torque with brake	12 Nm
perm. radial force acting on the locked dial plate	6000 N		perm. torque acting on running motor (steady)	33 Nm

Combined loads only after inspection by WEISS.

* Please consult WEISS for overhead mounting positions.

Timing diagram



Dimensions TW 150



Max. center line deviation between stationary center section and housing \pm 300 $^{\prime\prime}$

TW 200

Technical data

Cont. torque (Nm):	100	Cont. current (Arms):	3.12
Peak torque (Nm):	220	Peak current (Arms):	7
Max. speed (rpm):	120	Radial run out (mm):	0.02
Friction (Nm):	15	Axial run out at Ø 190 (mm):	0.02
Max. load (kgm²):	25	Thermal sensor:	PTC
Index precision ("):	±55	Internal inertia (kgm²):	0.031
Max. DC-Voltage (VDC):	800	Weight (kg):	42
Mounting Position:	any*	Gear ratio:	1:10
		All values in relation to the table-top	

Encoder

Interface Sick-Stegmann Hiperface			Interface Heidenhain EnDat (on request)		
Accuracy:	SEL52	±55"	Accuracy:	EQI	±55"

Load data (for the stationary center section)

		, ,			
perm. tilting moment acting on the center section	300 Nm	perm. force acting vertically on the center section	5000 N	perm torque acting on the center section	200 Nm
perm. radial force acting on the center section	4000 N				

Load data (for the rotary indexing dial plate)

perm. tilting moment acting on the locked dial plate	700 Nm	perm. operating force (acting verti- cally on the locked dial plate with the nominal Ø) 7500 N	perm. torque with brake	70 Nm
perm. radial force acting on the locked dial plate	8000 N		perm. torque acting on running motor (steady)	100 Nm

Combined loads only after inspection by WEISS.

* Please consult WEISS for overhead mounting positions.

Timing diagram



Dimensions TW 200



Max. center line deviation between stationary center section and housing \pm 300 $^{\prime\prime}$

TW 300

Technical data

Cont. torque (Nm):	200	Cont. current (Arms):	4.8
Peak torque (Nm):	450	Peak current (Arms):	12
Max. speed (rpm):	109	Radial run out (mm):	0.02
Friction (Nm):	20	Axial run out at Ø 280 (mm):	0.02
Max. load (kgm²):	50	Thermal sensor:	PTC
Index precision ("):	±45	Internal inertia (kgm²):	0.28
Max. DC-Voltage (VDC):	800	Weight (kg):	106
Mounting Position:	any*	Gear ratio:	1:11
		All values in relation to the table-top	

Encoder

Interface Sick-Stegmann Hiperface			Interface Heidenhain EnDat (on request)		
Accuracy:	SEL52	±45"	Accuracy:	EQI	±45"

Load data (for the stationary center section)

		3			
perm. tilting moment acting on the center section	1800 Nm	perm. force acting vertically on the center section	18000 N	perm torque acting on the center section	800 Nm
perm. radial force acting on the center section	2000 N				

Load data (for the rotary indexing dial plate)

perm. tilting moment acting 2250	perm. ope cally on the the nomin	ərating force (acting verti- 1e locked dial plate with 15000 N 1al Ø)	perm. torque witl	h brake 150 Nm	
perm. radial force acting on the locked dial plate 1500	0 N		perm. torque acti running motor (st	ing on teady) 200 Nm	

Combined loads only after inspection by WEISS.

* Please consult WEISS for overhead mounting positions.

Timing diagram



04/2014

Dimensions TW 300



WAS – WEISS Application Software

In addition to the basic functions of the start up, WAS - WEISS Application Software also gives you easy access to the teaching of positions and programming of motion-sequences. Your Windows-PC will be connected through RS232 or Ethernet with our drive.







Machine Layout TW

□ Enquiry □ Enclosure with order

Dear customer.

Thank you for your interest in our TW indexing tables. To ensure we supply the correct unit to suit your application, we kindly ask you to answer the following questions:

Model

- □ TW 150
- □ TW 200
- TW 300

Switching time

Based on the calculated mass inertia, do you require:

□ The shortest switching time

\Box A longer switching time of approx.		sec.
□ Angle of rotation		0
□ Standing time		sec
Total mass inertia:	k	a m²

Colour

□ RAL 7035 (light grey)

Special colour RAL ______ (for additional charges)

Electrical data

□ WEISS control system package

Amplifier, WAS - Software Cables length: □ 5m □ 10m □ 15m □ 20m □ 25m

Interfaces to the customer SPS

Digital I/O □ Free ASCII protocol

□ Ethernet

EtherNet/IP □ Modbus TCP

DeviceNet-CAN

CAN

Interfaces to WAS - WEISS Application Software

RS232 and Ethernet are included in the scope of delivery Converter USB to RS232

Electrical source

□ 1 or 3 x 208 ... 230V ~ 50/60Hz

□ 3 x 400 ... 480V ~ 50/60Hz (duty with TW300)

For technical enquiries

Adjustment connection plug





□ straight

□ 90°

Dial Plate

□ Included in the scope of offer and delivery Processing according to drawing No. _

Fixture and parts

Number:	
Weight per station:	kg
Diameter according the center to dr	rawing No.: mm

Extra indexing table

□ Included in the scope of offer and delivery Don't deliver Diameter: _____ _____ mm_Size: ______ mm Material Al St other

Encoder

- □ Hiperface (Standard with WEISS control package)
- □ EnDat (for third-party control systems)

Stationary center section

- above mounting level
- under mounting level (not with TW300)

Mounting position

- □ standard (vertical rotation axis)
- overhead (vertical rotation axis)
- horizontal rotation axis

Company:	Desired delivery date:	
Name:	Phone:	Fax:
Country:	email:	

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